

# eMG30

## 3D AUTOMATIC CONTROL SYSTEM FOR MOTOR GRADERS

The eMG30 system improve the construction quality and efficiency of earth moving engineering. The system adopts GNSS RTK high-precision positioning technology, IMU, and hydraulic control technology to calculate the three-dimensional coordinates of the grader blade in real time. And, according to the three-dimensional design drawings on the vehicle tablet, the blade attitude is controlled in real time, with absolute elevation accuracy of centimeters.



Machine Control

### Real-Time Automatic Blade Control

Its automatic real-time blade control adjusts the blade to the design surface, achieving finished grade accuracy in less time. One or two times the demand accuracy. It requires no more surveyor besides the motor grader, minimizes errors and rework, and significantly increases productivity.

### Easy Drive in Accuracy

It requires no more experienced motor grader driver. Automatic blade control system controls the blade based on the design, and drive the grader easily without any concern about the cutting performance.

### Convenient Operation

Sound prompts, such as operation and danger warning prompts, etc.  
Graphical and numerical indication of the relative position of the actual shovel blade and the design surface.  
3D visual guidance is intuitive and easy to understand, improving the smoothness of the working surface and ensuring rapid modeling.  
Work accurately even at night when the field of vision is limited.  
Support online version updates and quick registration.  
Support the generation of design files on the client side for faster construction.  
Support the import and export of coordinate conversion parameters and calibration files to speed up the system calibration process.  
Multiple calibration files can be stored and switched.

### Site Safety

Stakeless construction enhances the safety of the construction site.  
Electronic fence improves site safety.  
Precise and efficient. Reduce the driving requirements. Support rapid construction molding and quality control.  
Manual and automatic control modes can be effortlessly switched.



# Product Specification

## eMG30

### 3D AUTOMATIC CONTROL SYSTEM FOR MOTOR GRADERS



#### MA-2 Rugged GNSS Antenna

Signal received	<ul style="list-style-type: none"><li>■ GPS: L1/L2/L5</li><li>■ GLONASS: L1/L2/L3</li><li>■ BEIDOU: B1/B2/B3</li><li>■ Galileo: E1/E5a/E5b/E6</li><li>■ QZSS: L1/L2/L3/E6</li><li>■ IRNSS: L5</li><li>■ L-band</li></ul>
Nominal impedance	50Ω
Polarization	RHCP
Axial ratio	≤3dB
LNA Gain	40±2dB
Operation Current	≤45 mA
Dimension	Φ150×53mm
Connector	TNC female
Differential Transmission Delay	≤5 ns
Temperature	Working temperature: -45 - +85°C Storage temperature: -55 - +85°C
Waterproof	IP69K
Weight	≤600 g
Mounting	BSW5/8"-11 screw, depth10-11mm

#### MI-1 Inertial Sensor

Number of Axes	6 axes
Angular Velocity Range (°/s)	± 400
Acceleration Range (g)	± 8
Pitch Angle Range (°)	± 70
Roll Angle Range (°)	± 180
Roll/tilt Accuracy	0.15 deg
Resolution	0.01°
Output Data Rate	Selectable to 100 Hz
Output Rate	250 k - 1 M
Measurement Direction	X,Y,Z Axis
Signal Output	CAN2.0
Protection Class	IP67
Supply Voltage	5- 32 VDC
Power Consumption	< 100 mA
MTBF	≥ 50000 hours/ times
Shock Resistance	500g@11ms, 3-axis and same (half sine wave)
Vibration	10 - 2000 Hz; 13.9gRMS
Operating Temperature	-40 - +85 °C
Storage Temperature	-45 - +85 °C

#### Wiring

Definition	Pin
Power	6
GND	3
CAN High	1
CAN Low	2

#### MDP-1 Display

##### Performance Indicators

Channels	1408 channels, based on NebulasIV
Initialization	< 5 seconds (Typical)
Satellites Tracking	BDS:B1I, B2I, B3I, B1C, B2a, B26b GPS:L1C/A, L1C, L2P (Y), L2C, L5 GLONASS:L1, L2 Galileo:E1, E5a, E5b, E6 QZSS:L1, L2, L5, L6
Initialization Reliability	> 99.9%
Differential Format	RTCM3.3/3.2/3.1/3.0
Data Format	NMEA0183 Unicore
Observation Data Update Rate	20 Hz
Positioning Data Update Rate	20 Hz
Orientation Precision (RMS)	0.2°/1m
Timing Accuracy (RMS)	10 ns
Velocity Accuracy (RMS)	0.03 m/s
Positioning Accuracy (RMS)	RTK: H: 8 mm + 1 ppm; V: 15 mm + 1 ppm Single: H: 1.5 m; V: 2.5 m
Observation Accuracy(RMS)	BDS GPS GLONASS GALILEO
B1I/B1C/L1C/L1C/A/E1/G1 Code	10cm 10cm 10cm 10cm
B1I/B1C/L1C/L1C/A/E1/G1 Carrier phase	1mm 1mm 1mm 1mm
B3I/L2P(Y)/L2C/G2 Code	10cm 10cm 10cm 10cm
B2/L2P(Y)/L2C/G2 Carrier Phase	1mm 1mm 1mm 1mm
Time to First Fix (TTFF)	Cold Start < 10s Recapture < 1s
Radio	Supported frequencies 410-470Mhz Air baud rate 19200/9600 Protocol: TRIMTALK, TRIMMK3; TRANSEOT;SOUTH;SATEL

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MDP-1 Display	
Product Parameters	
GPU	8 Cores, Supports OpenGL ES 3.1
OS	Android 9.0
RAM	2 GB (Optional 4 GB)
ROM	16G ROM (Optional 64 GB), Support TF card (Expandable up to 256G)
Screen size	10.1 inch TFT LCD
Resolution	1024 x 600
Brightness	750 cd/m <sup>2</sup>
Touch panel	Capacitive (Supports five-finger touch)
Communications	2.4GHz/5.8GHz WiFi, IEEE 802.11 a/b/g/n/ac
	Supports WiFi hotspot sharing
	Supports Ethernet and 4G simultaneous online
	BT2.1+EDR/3.0/4.1LE/4.2BLE
	4G/LTE (Dual SIM optional)
	GNSS (GPS/BDS/GLONASS)
	Optional centimeter-level positioning board
	Optional inertial module
	Built-in microphone (optional)
I/O Interface	Built-in speaker
	RS-232*2
	RS-485*1
	Support 250K/500K CAN*1/2 (Support J1939,CANopen,ISO15765)
	DI*2, DO*2
	USB 2.0*1
	720p*4/1080p*2AHD camera inputs
	12V DC external power supply*2
	Ethernet*1

Product Parameters	
Power Management	9-36V DC input, support ignition detection
Water/dust Proof	IP65
Vibration Standards (at work)	MIL-STD-810
Shock Standards (at work)	ISO16750
Humidity Resistance	95% Non-condensing
Operating Temperature	-20°C - +70°C
Storage Temperature	-40°C - +85°C
Dimension(W*H*D)	281 mm x 181 mm x 42 mm
Weight	1.5 kg
Function Buttons	Power on/off button*1, Customized function buttons*2
Connector	Standard industrial grade waterproof connector
	SMA female*2 (GNSS & 4G)
	TNC female connector*2 (GNSS)

