

eME10

3D GNSS EXCAVATOR GUIDANCE SYSTEM

The eSurvey eME10 is designed with high accuracy in mind and consumes less time by guiding excavator operations. It employs GNSS real-time dynamic positioning technology to obtain the bucket's real-time and accurate 3D position information by reading multiple tilt sensors installed on the excavator. The eME10 features intuitive, easy-to-learn software that runs on the Android operating system. The state-of-the-art hardware and software help operators of all skill levels work faster and more efficiently than before, particularly in complicated environments. To summarize, you can accomplish more in less time.





Machine Control

Improved Accuracy

Bucket teeth with 3cm accuracy.

Visualized the blind spots and real-time guidance during the working process,

Results are displayed graphically and digitally for easy understanding.

Reduces over- and under-excavation while improving the general flatness of the excavation surface.

Easy Installation

One man can install all. Work faster and more efficiently by guiding excavator operations, quick for the installation and easy for the operator. Installation could setup on boom or machine body.

Lower Cost

No assistant is required; One person can complete the work. Reduce the requirements for the operator. No measurement or stake out is required; Simply start the machine and work. Reduce fuel consumption and mechanical loss to reduce operating costs.

Rugged Hardware

The eMEIO can be used for many years even under harsh environmental conditions (like dust, mud, rain, extreme heat, and cold) thanks to its rugged design of the display, GNSS receiver, positioning antenna, heading antenna, and tilt sensors.

Improved Efficiency

Simplified construction process, 50% higher efficiency.

Quick excavation, reduced rework, and guaranteed construction period.

24-hour construction without being affected by the environment

No fear of complex shapes;

One-time molding.

Fast Calibration

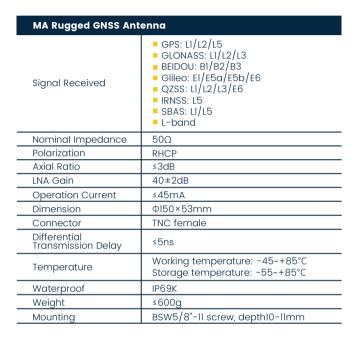
A new 3D modeling calibration method will provide customers with a brand-new way of measuring that does not require a total station. Easy and quick to learn and run; No need calculate the parameters on site.



Product Specification

eME10

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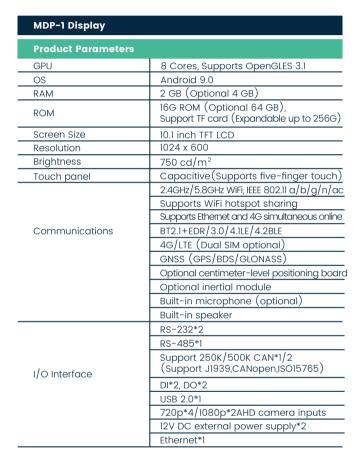


MI-2 Dynamic Inclination Signal Output	CAN2.0				
Water/dust Proof	IP68/IP69K				
MTTF	260 Years @ 40 °C				
Measuring Range	Pitch ± 85°, Roll ± 180°				
Absolute Accuracy	±0.30°				
Resolution	0.01°, ≤0.05°				
Repeatability	≤0.05°				
Dynamic Accuracy	≤0.05° ±0.5°				
Hysteresis	≤0.05°				
Mounting Direction	Vertical				
Supply Voltage	9- 30 VDC				
Power Consumption	≤ 65 mA @ 10 V DC, ≤ 60 mA @ 24 V DC				
Operating Temperature	-40 °C (-40 °F) - +75 °C (+167 °F)				
Storage Temperature	-40 °C (-40 °F) - +85 °C (+185 °F)				
Shock Resistance	≤ 100 g (half sine 6 ms, EN 60068-2-27)				
Vibration Resistance	1.5 mm (10 Hz – 58 Hz) & ≤ 20 g (58 Hz to 2000Hz				
Housing Materials	Die-cast aluminum alloy				
Potting Material	PUR (Polyurethane)				
Weight	220g (0.49 lb)				
Interface Protocol	J1939				
Stabilization Time	50 ms				
Transmission Rate	125 KBaud, 250 KBaud, 500 KBaud				
Default Transmission Rate	250kBaud				
Default Node ID	C0h				
Default PGN	PGN 65280 (Pitch, Roll, Acceleration x, Acceleration y) +PGN 65281 (Acceleration z,Gyro x, Gyro y, Gyro z)				
Reverse Polarity Protection	Yes				
Short Circuit Protection	Yes				
Certification Passed	CE + E1				

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Product Parameters			
Power Management	9-36V DC input, support ignition detection		
Water/dust Proof	IP65		
Vibration Standards (at work)	MIL-STD-810		
Shock Standards (at work)	IS016750		
Humidity Resistance	95% Non-condensing		
Operating Temperature	-20°C - +70°C		
Storage Temperature	-40°C - +85°C		
Dimension(W*H*D)	281 mm x 181 mm x 42 mm		
Weight	1.5 kg		
Function Buttons	Power on/off button*1, Customized function buttons*2		
Connector	Standard industrial grade waterproof connector		
COLLIBETOL	SMA female*2(GNSS & 4G)		
	TNC female connector*2 (GNSS)		



MDP-1 Display					
Performance Indicators					
Channels	1408 c	1408 channels, based on NebulasIV			
Initialization	<5 seconds (Typical)				
	BDS:B11, B21, B31, B1C, B2a, B26b				
	GPS:L1C/A, L1C, L2P (Y), L2C, L5				
Satellites Tracking	GLONASS:L1, L2				
	Galileo:E1, E5a, E5b, E6				
	QZSS:L1, L2, L5, L6				
Initialization Reliability	> 99.9%				
Differential Format	RTCM3.3/3.2/3.1/3.0				
Data Format	NMEA0183				
	Unicore				
Observation Data Update Rate	20 Hz				
Positioning Data Update Rate	20 Hz				
Orientation Precision (RMS)	0.2°/1m				
Timing Accuracy (RMS)	10 ns				
Velocity Accuracy (RMS)	0.03 m/s				
	RTK: H: 8 mm + 1 ppm;				
Positioning Accuracy (RMS)	V: 15 mm + 1 ppm				
	Single: H: 1.5 m; V: 2.5 m				
Observation Accuracy (RMS)	BDS	GPS		S GALILEO	
BII/BIC/LIC/LI C/A/EI/GI Code	10cm	10cm	10cm	10cm	
BII/BIC/LIC/LI C/A/EI/GI Carrier phase	lmm	lmm	lmm	lmm	
B3I/L2P(Y)/L2C/G2 Code	10cm	10cm	10cm	10cm	
B2/L2P(Y)/L2C/G2 Carrier Phase	lmm	lmm	lmm	lmm	
Time to First Firs (TTFF)	Cold Start < 10s				
Time to First Fix (TTFF)	Recapture < 1s				
	Supported frequencies 410-470Mhz				
Radio	Air baud rate 19200/9600				
	Protocol: TRIMTALK, TRIMMK3; TRANSEOT;SOUTH;SATEL				

O-survey



