

eMB10

3D GNSS GUIDANCE SYSTEM FOR BULLDOZERS

The eMB10 integrates multi-constellation precision positioning, sensor fusion, and real-time 3D guidance for bulldozer blade guidance or control. Using 3D data as a reference, the system rapidly meets design specs without traditional surveying.

The system enables round-the-clock operation by any operator, hence ensuring speedy and accurate task completion, reducing rework, and enhancing productivity and project profits.



Machine Control

Flexibility

- Support global coordinate library, suitable for global users, and provide multilingual versions.
- Support Athena engine RTK and L-Band China accuracy; Even without the base station, the intelligent receiver can reach centimeter-level accuracy.
- Support network differential.

Site Safety

- Stakeless construction enhances the safety of the construction site.
- Electronic fence improves site safety.
- Precise and efficient. Reduce the driving requirements. Support rapid construction molding and quality control.
- Manual and automatic control modes can be effortlessly switched.

Convenient Operation

- Sound prompts, such as operation and danger warning prompts, etc.
- Graphical and numerical indication of the relative position of the actual shovel blade and the design surface.
- 3D visual guidance is intuitive and easy to understand, improving the smoothness of the working surface and ensuring rapid molding.
- Work accurately even at night when the field of vision is limited.
- Support online version updates and quick registration.
- Support the generation of design files on the client side for faster construction.
- Support the import and export of coordinate conversion parameters and calibration files to speed up the system calibration process.
- Multiple calibration files can be stored and switched.

Real Validity

- Self-innovation technology achieves system accuracy of 3cm RMS.
- The digital construction management platform enables two-way transmission of design documents, construction tasks, and data to the cloud in real-time.
- The data is real and effective for managing remote quality and progress visualizations.



Product Specification

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MA-2 Rugged GNSS Antenna

Signal received	<ul style="list-style-type: none"> ■ GPS: L1/L2/L5 ■ GLONASS: L1/L2/L3 ■ BEIDOU: B1/B2/B3 ■ Galileo: E1/E5a/E5b/E6 ■ QZSS: L1/L2/L3/E6 ■ IRNSS: L5 ■ SBAS: L1/L5 ■ L-band
Nominal impedance	50Ω
Polarization	RHCP
Axial ratio	≤3dB
LNA Gain	40±2dB
Operation Current	≤45 mA
Dimension	Φ150×53mm
Connector	TNC female
Differential Transmission Delay	≤5 ns
Temperature	Working temperature: -45 - +85°C Storage temperature: -55 - +85°C
Waterproof	IP69K
Weight	≤600 g
Mounting	BSW5/8"-11 screw, depth10-11mm

MI-1 Inertial Sensor

Number of Axes	6 axes
Angular Velocity Range (°/s)	± 400
Acceleration Range (g)	± 8
Pitch Angle Range (°)	± 70
Roll Angle Range (°)	± 180
Roll/tilt Accuracy	0.15 deg
Resolution	0.01°
Output Data Rate	Selectable to 100 Hz
Output Rate	250 k - 1 M
Measurement Direction	X,Y,Z Axis
Signal Output	CAN2.0
Protection Class	IP67
Supply Voltage	5- 32 VDC
Power Consumption	< 100 mA
MTBF	≥ 50000 hours/times
Shock Resistance	500g@11ms, 3-axis and same (half sine wave)
Vibration	10 - 2000 Hz; 13.9gRMS
Operating Temperature	-40 - +85 °C
Storage Temperature	-45 - +85 °C

Wiring

Definition	Pin
Power	6
GND	3
CAN High	1
CAN Low	2

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MDP-1 Display		
Product Parameters		
GPU	8 Cores, Supports OpenGL ES 3.1	
OS	Android 9.0	
RAM	2 GB (Optional 4 GB)	
ROM	16G ROM (Optional 64 GB), Support TF card (Expandable up to 256G)	
Screen size	10.1 inch TFT LCD	
Resolution	1024 x 600	
Brightness	750 cd/m ²	
Touch panel	Capacitive(Supports five-finger touch)	
Communications	2.4GHz/5.8GHz WiFi, IEEE 802.11 a/b/g/n/ac	
	Supports WiFi hotspot sharing	
	Supports Ethernet and 4G simultaneous online	
	BT2.1+EDR/3.0/4.1LE/4.2BLE	
	4G/LTE (Dual SIM optional)	
	GNSS (GPS/BDS/GLONASS)	
	Optional centimeter-level positioning board	
	Optional inertial module	
I/O Interface	Built-in microphone (optional)	
	Built-in speaker	
	RS-232*2	
	RS-485*1	
	Support 250K/500K CAN*1/2 (Support J1939,CANopen,ISO15765)	
	DI*2, DO*2	
Product Parameters	USB 2.0*1	
	720p*4/1080p*2AHD camera inputs	
	12V DC external power supply*2	
	Ethernet*1	
	Power Management	9-36V DC input, support ignition detection
	Water/dust Proof	IP65
Vibration Standards (at work)	MIL-STD-810	
Shock Standards (at work)	ISO16750	
Humidity Resistance	95% Non-condensing	
Operating Temperature	-20°C - +70°C	
Storage Temperature	-40°C - +85°C	
Dimension(W*H*D)	281 mm x 181 mm x 42 mm	
Weight	1.5 kg	
Function Buttons	Power on/off button*1, Customized function buttons*2	
Connector	Standard industrial grade waterproof connector	
	SMA female*2(GNSS & 4G)	
	TNC female connector*2 (GNSS)	

MDP-1 Display					
Performance Indicators					
Channels	1408 channels, based on NebulasIV				
Initialization	< 5 seconds (Typical)				
Satellites Tracking	BDS:B1I, B2I, B3I, B1C, B2a, B26b				
	GPS:L1C/A, L1C, L2P (Y), L2C, L5				
	GLONASS:L1, L2				
	Galileo:E1, E5a, E5b, E6				
QZSS:L1, L2, L5, L6					
Initialization Reliability	> 99.9%				
Differential Format	RTCM3.3/3.2/3.1/3.0				
Data Format	NMEA0183				
Observation Data Update Rate	20 Hz				
Positioning Data Update Rate	20 Hz				
Orientation Precision (RMS)	0.2°/1m				
Timing Accuracy (RMS)	10 ns				
Velocity Accuracy (RMS)	0.03 m/s				
Positioning Accuracy (RMS)	RTK: H: 8 mm + 1 ppm; V: 15 mm + 1 ppm				
	Single: H: 1.5 m; V: 2.5 m				
Observation Accuracy(RMS)	BDS	GPS	GLONASS	GALILEO	
	B1I/B1C/L1C/L1C/A/E1/G1 Code	10cm	10cm	10cm	10cm
	B1I/B1C/L1C/L1C/A/E1/G1 Carrier phase	1mm	1mm	1mm	1mm
	B3I/L2P(Y)/L2C/G2 Code	10cm	10cm	10cm	10cm
B2/L2P(Y)/L2C/G2 Carrier Phase	1mm	1mm	1mm	1mm	
Time to First Fix (TTFF)	Cold Start < 10s				
	Recapture < 1s				
Radio	Supported frequencies 410-470Mhz				
	Air baud rate 19200/9600				
	Protocol: TRIMTALK, TRIMMK3; TRANSEOT;SOUTH;SATEL				

 **e-survey**