

Bestar 301

MULTI-FUNCTIONAL AUTO-STEERING SYSTEM

Independently developed by eSurvey GNSS, the eSurvey Bestar 301 is a multi-functional electric wheel-based auto-steering system.

The Bestar 301 could transfer farm work from fully manual driving to semi-automatic operation. It means high time efficiency and less operator fatigue. Based on the route planning algorithm, the vehicle could go through

the same paths every time to seed, spray and harvest with ±2.5 cm accuracy, which increases crop yield and reduces chemical usage.





Powerful satellite based signal service:

Using PPP(L-Band) enables
high-precision operation even when
CORS and other base station services
cannot be obtained.

Smart ECU: Easy configuration and upgrade

Bestar 301's ECU is based on a Linux system, allowing users to view position status, set up working mode, and update firmware from the Web user interface with any smartphone, tablet, or PC.

All-purpose System: Suitable for Various Types of Agricultural Machinery

Apply it to multiple types of agricultural machinery, including tractors, transplanters, sprayers, harvesters, etc., to make your farm work more effectively.

High Control Accuracy with Ultra-low Speed

Enable ±2.5 cm control accuracy even when the vehicle speed is as low as 0.2 km/h, and no longer need to worry about fine planting vegetables and fruit crops.

Easy Installation: No Need to Change Hydraulic Circuit

Install or remove it from your agricultural machinery as fast as 15 minutes.

24-hour Uninterrupted Work

Continuously work even in the day with heavy UV lights or at night. Free RTK aid function could maintain centimeter accuracy for 600 seconds when the Bestar 301 lost correction data.

Rich Optional Functions

Users could choose upgradable functions like 20 Hz DB9 NEMA direct output, dual camera, and ISOBUS-VT.



Bestar 301 System

| Accuracy | Dry land: 2.5 cm (<9 km/h); Paddy land: 5 cm (<9 km/h) |
|----------------------------|--|
| Line acquisition distance | <7 m |
| Vehicle velocity range | 0.2 - 18 km/h |
| Correction data source | GSM, Radio, SBAS, ALTPPP |
| Data formats | RTCM3.X, ROX, CMR, CMR+ |



Specification

| ST6 Display | |
|-------------|-------------------------------|
| System | |
| Processor | AllWINNER T507 8-core @1.5GHz |
| OS | Android 10.0 |
| RAM | 2 GB LPDDR4X |
| ROM | 16 GB eMMC |
| | |

| Screen | |
|-------------|---|
| Size | 10.1" LCD |
| Resolution | 1280 x 800 |
| Brightness | 750 nits |
| Touch panel | Capacitive touch screen, multi-point anti-glare |

| Communication | |
|---------------|---|
| Bluetooth | BT4.0 @BLE |
| Wi-Fi | 802.11 a/b/g/n 2.4 GHz |
| GSM | CATI LTE LTE FDD: BI/B3/B5/B7/B8/B20 TD-LTE: B38/B40/B4I GSM: B2/B3/B5/B8 |
| Port | Serial port (6-pin) x 1 Serial port (12-pin) x 2 USB type-A (USB host) x 1 USB (Micro-USB, USB device) x 1 SIM card (SDHC) x 1 Micro SD card (256G max) x 1 |

| Power Supply | |
|---------------|-------------|
| Input voltage | 6 - 36 V dc |

| Physical Specification | |
|------------------------|--------------------------|
| Dimension | 269 mm × 190 mm × 41 mm |
| Weight | 1300 g |
| Button | Power button x l |
| Battery | None |
| Humidity | 0-95% RH, non-condensing |
| Operating temperature | -20°C - +70°C |
| Storage temperature | -40°C - +85°C |
| Water/dust proof | IP65 |
| Vibration | ISO 16750/MIL-STD-810G |

| MC5 ECU (L-Band) | |
|---------------------------------|---|
| GNSS Performance | |
| Channels | 1100 |
| Satellites tracking | GPS: LIC/A, LIC, LIP, L2C, L2P, L5 BDS: BII, B2I, B3I, B1C, B2a, B2b, ACEBOC GLONASS: GI, G2, G3 GALILEO: EI, E5a, E5b, ALTBOC, E6 QZSS: LIC/A, LIC, L2C, L5, LEX SBAS, L-Band |
| Update rate | 20Hz |
| Horizontal positioning accuracy | Single: < 1.2 m (RMS)DGNSS: < 0.3 m (RMS)RTK: 8 mm+1 ppm (RMS) |
| Heading accuracy | < 0.2° rms with 1.0 m baseline |
| Re-acquisition | < 1 second |

| Communication | |
|---------------|--|
| Bluetooth | 4.2 |
| Wi-Fi | IEEE 802.11 b/g/n |
| GSM | Global GSM/WCDMA/LTE |
| Port | 1 x serial port, 18-pin 1 x SIM card 1 x GNSS heading, TNC 1 x UHF, TNC |

| Internal Radio | |
|-----------------|---|
| Frequency range | 410 - 470 MHz & Hopping 902.4 - 928 MHz |
| Channel spacing | 12.5 KHz / 25 KHz |
| Protocol | HZSZ, TrimTalk 450S, PCC-GMSK, South |
| | |

| Environment | |
|-----------------------|--------------------------------|
| Operating temperature | -40°C - +70°C |
| Storage temperature | -40°C - +85°C |
| Humidity | 95% |
| Shock | EP 455 Section 5.14.1 |
| Vibration | EP 455 Section 5.15.1 (Random) |
| Water/dust proof | IP67 |

| Power | |
|---------------|---------------------------------|
| Input voltage | 9 – 28 V dc (ISO 16750 4.2 B-H) |

| Physical Specification | |
|------------------------|-------------------------------|
| Dimension | 162.2 mm × 162.8 mm × 70.2 mm |
| Material | Magnesium alloy |
| Weight | 1284±20 g |

Specification

| EW2 Electric Steering Wheel | |
|-----------------------------|-------------|
| Motor | |
| Working voltage | 9 - 32 V dc |
| Nominal voltage | 12 V dc |
| Output torque | ≥6.5N•m |
| Maximum output torque | 13 N·m |
| Maximum power | < 200 W |
| Maximum rotation speed | 100 RPM |
| Load steering error | < ±5° |
| Response delay | 20Hz |

| Working Environment | |
|---------------------------|---------------------------------|
| Operating temperature | -20°C - +70°C (-68°F - +158°F) |
| Storage temperature | -40°C - +85°C (-104°F - +185°F) |
| Mechanical shock | EP455/5.14.1 |
| Vibration characteristics | EP455/5.15.1& 5.15.2 |

| Communication | |
|------------------------|------------------------|
| Interface | ALTW/IDC-06PMMS-LC7001 |
| Communication protocol | ISO11783 CAN BUS |

| EMC / Safety / Environmental Protection | |
|---|---|
| Radiated interference | Broadband: IAW ISO14982-2009 /6.4Narrowband: IAW ISO14982-2009 / 6.5 |
| Radiation immunity | IAW ISO14982-2009/6.6 |
| Electrostatic discharge (ESD) | IAW ISO14982-2009/6.7 |
| Environmental protection standard | 2011/65/EU ROHS 2.0 |

| Physical Specification | 1 |
|------------------------|-----------------|
| Dimensions | Ф180 mm × 80 mm |
| Weight | 4.6 kg |

| Rear Camera (Optional) | |
|------------------------|------------------------|
| Performance | |
| Water/dust proof | IP67 |
| Input voltaget | 12 V dc |
| Port | Female, 4-pin aviation |
| LED | 8 LED light |
| Resolution | 720P, 1024 x 600 |

| P300 GNSS Antenna(Optional) | | |
|-----------------------------|--|--|
| Antenna Performance | Antenna Performance | |
| Frequency | GPS: L1, L2, L5 BDS: B1, B2, B3 GLONASS: G1, G2, G3 GALILEO: E1, E5 QZSS | |
| Polarization | Right-handed circular | |
| Axis ratio | ≤2dB @Axial | |
| Antenna gain | GPS L1: > 6 dBiGPS L2: > 5 dBi | |
| Phase center offset | ±2 mm | |

| Physical Specification | |
|------------------------|-----------------|
| Dimensions | Ф146 mm x 46 mm |
| Weight | 500 g |
| Antenna interface | TNC-F |
| Radome material | ASA Plastic |
| Base material | Aluminum alloy |
| Mount | 5/8-11UNC-2B |

iMM1 Angle Sensor & iMM1 External IMU (Optional)

| Performance | |
|---------------------|--------------|
| Supply voltage | 5.5 - 36 V |
| Supply current | 30 mA/12 V |
| Power consumption | ≤ 0.7 W |
| Water/dust proof | IP67 |
| Measurement range | ±90° |
| Measurement axis | X-Y |
| Resolution | 0.002° |
| Accuracy | 0.1° |
| Update rate | 50 Hz |
| Initialization time | ≤ 30 seconds |

| Working Environment | |
|---------------------|-------------------------------|
| Working temperature | -40°C - +70°C |
| Storage temperature | -40°C - +85°C |
| Shock | 20000 g, 0.5 ms, 3 times/axis |
| Interface | CAN |

| Physical Specification | 1 |
|------------------------|----------------|
| Material | Aluminum alloy |



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